Agents: Definitions & Conceptual Framework

Distributed Systems
Sistemi Distribuiti

Andrea Omicini
andrea.omicini@unibo.it

Dipartimento di Informatica – Scienza e Ingegneria (DISI)
Alma Mater Studiorum – Università di Bologna a Cesena

Academic Year 2015/2016
1 Autonomy

2 Definitions
Outline

1. Autonomy

2. Definitions
Autonomy as the Foundation of the Definition of Agent

Lex Parsimoniae: Autonomy
- Autonomy as the only fundamental and defining feature of agents
- Let us see whether other typical agent features follow / descend from this somehow

Computational Autonomy
- Agents are autonomous as they encapsulate (the thread of) control
- Control does not pass through agent boundaries
  - only data (knowledge, information) crosses agent boundaries
- Agents have no interface, cannot be controlled, nor can they be invoked
- Looking at agents, MAS can be conceived as an aggregation of multiple distinct loci of control interacting with each other by exchanging information
(Autonomous) Agents (Pro-)Act

Action as the essence of agency

- The etymology of the word *agent* is from the Latin *agens*
- So, agent means “the one who acts”
- Any coherent notion of agency should naturally come equipped with a model for agent actions

Autonomous agents are pro-active

- Agents are literally active
- Autonomous agents encapsulate control, and the rule to govern it
  → Autonomous agents are pro-active by definition
    - where pro-activity means “making something happen”, rather than waiting for something to happen
Agents are Situated

The model of action depends on the context

- Any “ground” model of action is strictly coupled with the context where the action takes place
- An agent comes with its own model of action
- Any agent is then strictly coupled with the environment where it lives and (inter)acts
- Agents are in this sense are intrinsically *situated*
Situatedness and reactivity come hand in hand

- Any model of action is strictly coupled with the context where the action takes place.
- Any action model requires an adequate *representation* of the world.
- Any *effective* representation of the world requires a *suitable* balance between environment *perception* and representation.

→ Any effective action model requires a suitable balance between environment perception and representation.

- however, any non-trivial action model requires some form of perception of the environment—so as to check action pre-conditions, or to verify the effects of actions on the environment.
- Agents in this sense are supposedly *reactive* to change.
Are Autonomous Agents Reactive?

Reactivity as a (deliberate) reduction of proactivity

- An autonomous agent could be built / choose to merely react to external events
- It may just wait for something to happen, either as a permanent attitude, or as a temporary opportunistic choice
- In this sense, autonomous agents may also be reactive

Reactivity to change

- Reactivity to (environment) change is a different notion
- This mainly comes from early AI failures, and from robotics
- It stems from agency, rather than from autonomy—as discussed in the previous slide
- However, this issue will be even clearer when facing the issue of artifacts and environment design
(Autonomous) Agents Change the World

Action, change & environment

- Whatever the model, any model for action brings along the notion of change
  - an agent acts to change something around in the MAS
- Two admissible targets for change by agent action
  - **agent** an agent could act to change the state of another agent
    - since agents are autonomous, and only data flow among them, the only way another agent can change their state is by providing them with some information
    - change to other agents essentially involves *communication actions*
  - **environment** an agent could act to change the state of the environment
    - change to the environment requires *pragmatical actions*
    - which could be either physical or virtual depending on the nature of the environment
Autonomous Agents are Social

From autonomy to society

- From a philosophical viewpoint, autonomy only makes sense when an individual is immersed in a society
  - autonomy does not make sense for an individual in isolation
  - no individual alone could be properly said to be autonomous
- This also straightforwardly explains why any program in any sequential programming language is not an autonomous agent *per se* [Gra96, Ode02]

Autonomous agents live in a MAS

- Single-agent systems do not exist in principle
- Autonomous agents live and interact within agent societies & MAS
- Roughly speaking, MAS are the only “legitimate containers” of autonomous agents
Autonomous Agents are Interactive

Interactivity follows, too

- Since agents are subsystems of a MAS, they interact within the global system
  - by essence of systems in general, rather than of MAS
- Since agents are autonomous, only data (knowledge, information) crosses agent boundaries
- Information & knowledge is exchanged between agents
  - leading to more complex patterns than message passing between objects
Autonomous Agents Do not Need *Exactly* a Goal

Agents govern MAS computation

- By encapsulating control, agents are the main forces governing and pushing computation, and determining behaviour in a MAS.
- Along with control, agents should then encapsulate the *criterion* for regulating the thread(s) of control.

Autonomy as self-regulation

- The term “autonomy”, at its very roots, means self-government, self-regulation, self-determination.
  - “internal unit invocation” [Ode02]
- This does *not* imply in any way that agents *needs* to have a goal, or a task, to be such—to be an agent, then.
- However, this *does* imply that autonomy captures the cases of goal-oriented and task-oriented agents.
  - where goals and tasks play the role of the criteria for governing control.
Goal-/Task-Orientedness is not a Defining Feature for Agents

Example: finite-state automaton with encapsulated control
- An agent might be a finite-state automaton
- Encapsulating control as an independent thread
- Equipped with state transition rules
- The criteria for the govern of control would there be embodied in terms of (finite) states and state transition rules

Goal-orientedness and task-orientedness are just possible features for agents
- They are not defining features anyway
Outline

1 Autonomy

2 Definitions
“Weak” Notion of Agent

Four key qualities [WJ95]

Weak agents are
- Autonomous
- Proactive
- Reactive (to change)
- Social
Are Autonomous Agents Intelligent?

Intelligence helps autonomy

- Autonomous agents have to self-determine, self-govern, . . .
- Intelligence makes it easy for an agent to govern itself
- While intelligence is not mandatory for an agent to be autonomous
  - however, *intelligent autonomous agents* clearly make sense
Are Autonomous Agents Mobile?

Mobility is an extreme form of autonomy

- Autonomous agents encapsulate control
- At the end of the story, control might be independent of the environment where an agent lives—say, the virtual machine on which it runs
- *Mobile autonomous agents* clearly make sense
  - mobility, however, is *not* required for an agent to be autonomous
Do Autonomous Agents Learn?

Learning may improve agent autonomy

- By learning, autonomous agents may acquire new skills, improve their practical reasoning, etc.
- In short, an autonomous agent could learn how to make a better use out of its autonomy
- *Learning autonomous agents* clearly make sense
  - learning, however, is *not* required for an agent to be autonomous
“Strong” Notion of Agent

Mentalistic notion [WJ95]

Strong agents have mental components such as
- Belief
- Desire
- Intention
- Knowledge
- ... 

Intelligent agents and mental components

Intelligent autonomous agents are naturally (and quite typically) conceived as strong agents
Summing Up

Definition (Agent)

Agents are *autonomous computational entities*

- **genus** agents are computational entities
- **differentia** agents are autonomous, in that they encapsulate control along with a criterion to govern it

Agents are autonomous

- From autonomy, many other features stem
  - autonomous agents *are* interactive, social, proactive, and situated;
  - they *might* have goals or tasks, or be reactive, intelligent, mobile
  - they live within MAS, and *interact* with other agents through *communication actions*, and with the environment with *pragmatical actions*
1 Autonomy

2 Definitions
Stan Franklin Art Graesser.
Is it an agent, or just a program?: A taxonomy for autonomous agents.

James Odell.
Objects and agents compared.
Michael Wooldridge and Nicholas R. Jennings.
Intelligent agents: Theory and practice.
Agents: Definitions & Conceptual Framework

Distributed Systems
Sistemi Distribuiti

Andrea Omicini
andrea.omicini@unibo.it

Dipartimento di Informatica – Scienza e Ingegneria (DISI)
Alma Mater Studiorum – Università di Bologna a Cesena

Academic Year 2015/2016